#### ľ Daido Precision Industries Ltd.

3 Fl. Nishi-Ikebukuro TS BLDG., 1-15 Nishi-Ikebukuro 3-Chome, Toshima-ku, Tokyo 171, Japan Tel. 03-5956-9176 Fax. 03-5956-9177

# MICROCOUPLING





## **Popularity Gained Through Use In Various Fields Such As Mechatronics, And Others**

#### Microcoupling are:

Compact size plate spring type precision shaft coupling that have made debut in the first place in Japan.

Plate springs vital to this type shaft coupling are derivative from sheet metal fabricating technique, the expertise unique to us being accumulated for nearly one half a century.

Making debut in 1975 and with acquired abundant experience and providing good results since, microcoupling are now used widely in variety of fields such as measuring instruments and machine tools, robots, semiconductors and so on that are leading the era's industries.

Wide products line, ranging from High precision, high torque products to reasonably priced products. Products homogenized in quality meeting the needs of the era derived from a vertically integrated production system form designing through manufacturing to inspection.



•Component parts mechanically connected afford for precise rotation control.

## **High Power For Absorbing Eccentricity/Declination**

•High fatigue resistance of plate springs allows for provision of a high power for absorbing eccentricity and declination. •Increasing distance between plate springs allows for making higher power for absorbing eccentricity without changes take place with power for absorbing eccentricity, thus facilitating centering.



•Utilization of resiliency, a property of plate springs, provides high resonance frequency and precise responding characteristic.

Microcoupling

**M** Series (Standard Type)

V Series (Enhanced Torque Type)

**Microflex U** Series (Low Torque · Low Cost Type Super Small Size)

lubrication.

### **Greater Torque Capacity**

- •Transmission of torque developed by plate springs as simple tractive force allows for provision of greater torque capacity as compared to those using shearing strength.
- •Use of high tensile steel provides tenacity against intense right and reverse rotation.

1

### **Greater Degree of Freedom For Each Part**

•Connecting respective parts based upon machine elements allows changes in parts composition, thus meeting all needs arising depending upon application.





### **Longer Useful Life Dispense** With Maintenance

•Having no sliding parts eliminates wearing, thus allowing continuous operation for extensive period of time without





## **Microcoupling For High Precision And High Quality Without Backlash**

#### 

	M Series V Series		U Series	
Series	Standard Type	Enhanced Torque Type	Low-torque, Low-cost Type	
Torque	1.5~15 N⋅m	6~20 N⋅m	0.3~1.0 N⋅m	
Material	Aluminum Alloy	Carbon Steel	Aluminum Alloy	
Major Application	Servo System Rotation Detector Servo-motor Feed Screw	Servo-motor Feed Screw	General Rotation Detector Small Size Motor Small Size Feed Screw	

è φ 25

Ĕg φ 20

φ *φ* 15

φ 10

U-

-M3

-M4

0 1525

Flexible Plate

Hub

#### Selection Base 2 Model Number

#### 1. Transmission of Torque

Select a coupling so that a design torque as derived from following formula to be within a rated torque for such a coupling.

x <u>P</u> x K
= Design Torque
= Rated Output
= Rated Rotating Speed
= Load Coefficient
Servo-motor Driving)

#### 2. Transmission of Rotation

For driving measuring instrument, select a coupling with consideration of performance characteristics and allowable load, in main, and relative variation in two working shafts and centering precision.

#### Shaft Fixing system 3 Type



3





#### Model and Type

\_

\_

\_

\_

\_

\_

\_

\_





#### Optional Specification 6 Suffixed Symbol

- Those requiring Lesser torque but Larger shaft diameter.
- Those requiring greater torsional rigidity.
- Those requiring shortened full Length (L Dimension)
- Those requiring greater space between shafts. (D Dimension)
- Those requiring insertion of slit plates for 0 point setting.

• Those requiring use in vacuum atmosphere. \*for details, please contact us



4

#### Axial Directional Displacement and Allowance for Declination

te , 3.	.0				
Axial Directional Displacen	.0				M1 M2 M3 M4
	(	0.5	i 1.	.0 1.	5 (°)
			Declination		

#### Allowance for declination varies depending upon axial directional displacement

•Longer useful life will be achieved by maintaining axial directional displacement and declination within the values above •Axial directional displacement represents a value per one set of coupling

•Declination represents a value per one set of flexible plates.(plate springs)

#### Axial Directional Displacement and Thrusting Force



Greater axial directional displacement is absorbed by lesser thrusting force

 Axial directional displacement and thrusting force, respectively represents a value per one set of coupling.

•Thrusting force is proportional to axial directional displacement

#### Torque and Torsional Angle



High torsional rigidity can be enhanced further Torsional angle is proportional to torque •Torsional angle represents a value per one set of coupling

Note) Above diagrams are examples of observed values for M Series.

#### Condition on Delivery

- Assembled products with finished bores are delivered
- "H7" is the standard tolerance for bores
- "H7, F7, P9, Js9" are standard tolerance for key way width
- Standard for screw holes vary depending upon models (for details, see P5~P9)

### **M Standard Series**

Rated Torque Torsional Rigidity Maximum Rotating S Working Temperatu Range of Bore Diam			Torque nal Rigidity um Rotating Sp ng Temperature of Bore Diame	15 7.3 peed 20 Range -30 ter φ 8	N·m $3X10^{3}N\cdotm/rad$ $,000min^{-1}$ $0 \sim +100 ^{\circ}C$ $3 \sim \phi 25$
	Fixing System	Set-Screv	w System	Clamping	g System
ltem	Unit/Symbol	M1A-[]/[]	M1F/	M1AC-	M1FC-
Inertia (GD <sup>2</sup> /4)	kg ∙ m²	98 X 10-6	98 X 10-⁵	120 X 10-6	100 X 10-6
Max. Misalignment (Angular/Parallel)	%mm	1.5 <sup>0</sup> / 0.7	1.5 <sup>0</sup> / 0.3	1.5 <sup>0</sup> / 0.7	1.5 <sup>0</sup> / 0.3
Weight	kg	0.28	0.23	0.30	0.24
Outer Diameter	A	φ!	57	φ 57	
Boss Diameter	В	φ31 (φ	57)*note1	φ 44 (φ 57)*note 1	
Bore Diameter	С	φ8~φ20 (φ2	1~φ 25)*note1	φ 8~φ 18 (φ 19~φ 22)*note1	
Space Between shaft	D	34.5	20.5	34.5	20.5
Length of Hub	E	20		20	
Full Length	L	74.5	60.5	74.5	60.5
Screw Position	1	-	7	6	
Screw Hole	Р	2-M6		1-1	W5

■Body Material:Aluminum alloy ■Flexible Plates:Stainless steel ■Bolt/Washer:Carbon steel





\*Note 1 : Inner diameter in () is for a hub with greater boss diameter. Note 2 : Maximum shaft diameter for that goes through inner diameter in flexible plates and

spacers is  $\phi 19$ . Note 3 : Unit for figures without mention of unit is <mm>.

 $\phi$  7.8

•M1A-15K/15K

•M1FC-14BC/14BC

MZ	
----	--

Tentative Hole Diameter

■Rated Torque 15N∙m Torsional Rigidity 1.7X10<sup>3</sup>N·m/rad Maximum Rotating Speed 20,000min<sup>\*</sup> Working Temperature Range -30 ~ +100 °C Range of Bore Diameter  $\phi\,6\sim\phi\,20$ 

 $\phi$  7.8

	Fixing System	Set-Screw System		Clampin	g System
Item	Type Unit/Symbol	M2A-[]/[]	M2F/	M2AC-	M2FC-
Inertia (GD <sup>2</sup> /4)	kg · m²	19 X 10-6	19 X 10⁴	20 X 10-6	20 X 10-⁵
Max. Misalignment (Angular/Parallel)	%mm	1.5%	/ 0.3	1.5% 0.3	
Weight	kg	0.080	0.075	0.080	0.075
Outer Diameter	А	φ 42		φ.	42
Boss Diameter	В	φ 26 (φ 42)*note1	<i>ф</i> 26	<i>φ</i> 32	<i>ф</i> 26
Bore Diameter	С	φ6~φ16 (φ17~φ20)	<i>φ</i> 6~ <i>φ</i> 16	φ6~φ16	<i>φ</i> 6~ <i>φ</i> 14
Space Between shaft	D	13	.8	13.8	
Length of Hub	E	16	12.5	16	12.5
Full Length	L	45.8	38.8	45.8	38.8
Screw Position	1	7.5	4	5	4
Screw Hole	Р	2-M4		1-M4	1-M3
Tentative Hole	-	ø 5.8		φ!	5.8

М1 \*Note 1 : Inner diameter in () is for a hub with greater boss diameter. M2

**Standard Series** 

М3

Note 2 : Maximum shaft diameter for that goes through inner diameter in flexible plates and spacers is  $\phi$ 14. M4

Note 3 : Unit for figures without mention of unit is <mm>.





●M2FC-10BC/10BC

**M Standard Series** 



Rated Torque	2.5N·m
Torsional Rigidity	0.33X10 <sup>3</sup> N·m/rad
Maximum Rotating Speed	20,000min <sup>-1</sup>
Working Temperature Range	-30 ~ +100 ⁰C
Range of Bore Diameter	φ3~φ15

	Fixing System	Set-Screw System		Clamping System
Item	Type Unit/Symbol	M3A-[]/[]	M3F-[]/[]	M3AC-
Inertia (GD <sup>2/4</sup> )	kg ∙ m²	3.0 X 10 <sup>-6</sup>	2.5 X 10-6	3.2 X 10 <sup>-6</sup>
Max. Misalignment (Angular/Parallel)	%mm	1.5 <sup>0</sup> / 0.2	1.5 <sup>°</sup> / 0.15	1.5 <sup>0</sup> / 0.2
Weight	kg	0.032	0.024	0.030
Outer Diameter	A	φ 32		<i>φ</i> 32
Boss Diameter	В	φ 18 (φ 32)*note1 φ 18		<i>φ</i> 18
Bore Diameter	С	φ 3~φ 10 (φ 11~φ 15)	φ3~φ10	φ 4~φ 9.525
Space Between shaft	D	11.4	8.6	11.4
Length of Hub	E	12	8	12
Full Length	L	35.4	24.6	35.4
Screw Position	1	5 (6) 3		4
Screw Hole	Р	2-M4		1-M2.6 (φ4~φ8) 1-M2 (φ4~φ9.525)
Tentative Hole Diameter	-	φ2.8		φ <b>3.8</b>

\*Note 1 : Inner diameter in () is for a hub with greater boss diameter.

Note 2 : Maximum shaft diameter for that goes through inner diameter in flexible plates and spacers is \$\phi10\$. Note 3 : Unit for figures without mention of unit is <mm>.



Rated Torque 1.5N·m Torsional Rigidity 0.23X10<sup>3</sup>N·m/rad Maximum Rotating Speed 20,000min<sup>\*</sup> Working Temperature Range -30 ~ +100 °C φ 3 ~ φ 10 Range of Bore Diameter

	Fixing System	Set-Screw System		Clamping System
Item	Type Unit/Symbol	M4A-[]/[]	M4F-□/□	M4FC-[]/[]
Inertia (GD <sup>2/4</sup> )	kg · m²	2.5 X 10*	3.0 X 10 <sup>-6</sup>	3.0 X 10-6
Max. Misalignment (Angular/Parallel)	%mm	1.5°	/ 0.2	1.5 <sup>°</sup> / 0.2
Weight	kg	0.032	0.025	0.036
Outer Diameter	А	φ26		<i>ф</i> 26
Boss Diameter	В	-		-
Bore Diameter	С	φ3~φ10		<i>φ</i> 4~ <i>φ</i> 8
Space Between shaft	D	11.4 10		10
Length of Hub	Е	8	6	11
Full Length	L	27.4 22		32
Screw Position	1	4 3		3
Screw Hole	Р	2-1	<b>V</b> I3	1-M2.6
Tentative Hole Diameter	-	φ2.8		φ <b>3</b> .8

Note 1 : Maximum shaft diameter for that goes through inner diameter in flexible plates and spacers is  $\phi$ 7. Note 2 : Unit for figures without mention of unit is <mm>.

6

	-
•M2A-10S/10S	

5

■Body Material:Aluminum alloy ■Flexible Plates:Stainless steel ■Bolt/Washer:Carbon steel







### **V Enhanced Torque Series**

	■Rated Torque	20N·m
4	■Torsional Rigidity	7.3X10 <sup>3</sup> N·m/rad
	Maximum Rotating Speed	20,000min <sup>-1</sup>
	Working Temperature Range	-30 ~ +100 ⁰C
	Range of Bore Diameter	φ 8 ~ φ 25

	Fixing System	Set-Screw System	Clamping System	Taper System	
ltem	Type Unit/Symbol	V1F-[]/[]	V1FC-	V1FB-11T/	V1FB-16T/73.5
Inertia (GD <sup>2</sup> /4)	kg · m²	220 X 10⁴	300 X 10-6	240 X 10-6	280 X 10 ⁵
Max. Misalignment (Angular/Parallel)	%mm	1.5 <sup>0</sup> / 0.3	1.5 <sup>0</sup> / 0.3	1.5°	/ 0.3
Weight	kg	0.48	0.60	0.55	0.60
Outer Diameter	А	φ57	φ57	φ57	
Boss Diameter	В	φ 31 (φ 57)*note1	φ 44 (φ 57)*note 1	φ 44 (φ 57)*note 1	
Bore Diameter	С	φ 8~φ 20 (φ 21~φ 25)*note1	φ 8~φ 18 (φ 19~φ 22)*note1	φ 8~φ 18 (φ 19~φ 22)*note1	
Space Between shaft	D	20.5	20.5	20.5	
Length of Hub	E	20	20	2	0
Full Length	L	60.5	60.5	60.5	73.5
Screw Position	1	7	6	6	
Screw Hole	Р	2-M6	1-M5	1-M5	
Tentative Hole Diameter	-	φ7.8	φ7.8	φ7.8	

\*Note 1 : Inner diameter in () is for a hub with greater boss diameter.

Note 2 : Maximum shaft diameter for that goes through inner diameter in flexible plates and spacers is  $\phi$ 20. Note 3 : Unit for figures without mention of unit is <mm>.

Body Material:Carbon steel
■Flexible Plates:Stainless steel
■Bolt/Washer:Carbon steel
Bolt/Washer:Carbon steel





●V1FB-11T/12BC

7

●V1FB-16T/14BC-73.5

- ■Rated Torque 6N∙m Torsional Rigidity 1.7X10<sup>3</sup>N·m/rad Maximum Rotating Speed 20,000min<sup>-1</sup> Working Temperature Range -30 ~ +100 ⁰C Range of Bore Diameter  $\phi\,6\sim\phi\,20$

	Fixing System	Set-Screw System	Clamping System	Taper System
ltem	Type Unit/Symbol	V2A-[]/[]	V2AC/	V2AB-11T/
Inertia (GD <sup>2</sup> /4)	kg ∙ m²	54 X 10-6	300 X 10⁴	240 X 10-⁵
Max. Misalignment (Angular/Parallel)	%mm	1.5 <sup>0</sup> / 0.3	1.5 <sup>0</sup> / 0.3	1.5 <sup>°</sup> / 0.3
Weight	kg	0.19	0.20	0.20
Outer Diameter	А	φ42	φ42	<i>φ</i> 42
Boss Diameter	В	φ 26 (φ 42)*note1	<i>φ</i> 32	φ32
Bore Diameter	С	φ6~φ16 (φ17~φ20)*note1	<i>φ</i> 6~ <i>φ</i> 16	<i>\$</i> 6~ <i>\$</i> 16
Space Between shaft	D	13.8	13.8	13.8
Length of Hub	E	16	16	16
Full Length	L	45.8	45.8	45.8
Screw Position	1	7.5	5	5
Screw Hole	Р	2-M4	1-M4	1-M4
Tentative Hole Diameter	-	φ5.8	φ5.8	φ 5.8

**V1** \*Note 1 : Inner diameter in () is for a hub with greater boss diameter. **V2** 

**Enhanced Torque** 

• Series

Note 2 : Maximum shaft diameter for that goes through inner diameter in flexible plates and spacers is  $\phi$ 14.

Note 3 : Unit for figures without mention of unit is <mm>.





### **U Microflex Series**

	U	15
--	---	----

Rated Torque	1.0N·m
Torsional Rigidity	0.35X10 <sup>³</sup> N⋅m/rad
Maximum Rotating Speed	30,000min <sup>-1</sup>
Working Temperature Range	-30 ~ +100 °C
Range of Bore Diameter	$\phi 4 \sim \phi 13$

	Fixing System	Set-Screw System	Clamping System
Item	Type Unit/Symbol	U15A-[]/[]	U15FC/
Inertia (GD <sup>2</sup> /4)	kg · m²	3.8 X 10 <sup>-6</sup>	4.0 X 10 <sup>-6</sup>
Max. Misalignment (Angular/Parallel)	º/mm	1.5º/ 0.3	1.5 <sup>°</sup> / 0.2
Max. Axial Displacement	mm	0.7	0.7
Weight	kg	0.034	0.040
Outer Diameter	A	<i>ф</i> 28	<i>ф</i> 28
Bore Diameter	С	φ4~φ13	φ4~φ13
Space Between shaft	D	14	9
Length of Hub	E	8	10.5
Full Length	L	30	30
Screw Position	1	4	3.5
Screw Hole	Р	2-M4	1-M3
Tentative Hole Diameter	-	φ3.8	φ <b>3.8</b>

\*Note 1 : Inner diameter in () is for a hub with greater boss diameter.

Note 2 : Maximum shaft diameter for that goes through inner diameter in flexible plates and spacers is  $\phi$ 13. Note 3 : Unit for figures without mention of unit is <mm>.

U	2	<ul> <li>Ratect</li> <li>Torsic</li> <li>Maxim</li> <li>Worki</li> <li>Range</li> </ul>
		·

Rated Torque	0.3N·m
Torsional Rigidity	0.18X10 <sup>3</sup> N⋅m/rad
Maximum Rotating Speed	30,000min <sup>-1</sup>
Working Temperature Range	-30 ~ +100 °C
Range of Bore Diameter	φ 2 ~ φ 10

	Fixing System	Set-Screw System	Clamping System
ltem	Type Unit/Symbol	U2F/	U2FC-[]/[]
Inertia (GD <sup>2/4</sup> )	kg ∙ m²	10 X 10-6	1.5 X 10-⁵
Max. Misalignment (Angular/Parallel)	%mm	1.5º/ 0.15	1.5 <sup>°</sup> / 0.2
Max. Axial Displacement	mm	0.5	0.5
Weight	kg	0.014	0.022
Outer Diameter	А	<i>φ</i> 21	φ21
Bore Diameter	С	φ2~φ10	<i>φ</i> 3~ <i>φ</i> 8
Space Between shaft	D	8	11
Length of Hub	E	6	9.5
Full Length	L	20	30
Screw Position	1	3	3
Screw Hole	Р	2-M3	1-M2.6
Tentative Hole	-	φ1.8	φ2.8

\*Note 1 : Inner diameter in () is for a hub with greater boss diameter.

Note 2 : Maximum shaft diameter for that goes through inner diameter in flexible plates and spacers is *φ*8. Note 3 : Unit for figures without mention of unit is <mm>.

■Body Material:Aluminum alloy ■Flexible Plates:Stainless steel Bolt/Washer:Carbon steel



**U** Microflex Series

U15 U2

#### **U** Microflex Series

		_	
		Rated Torque	0.3N·m
		Torsional Rigidity	0.10X10 <sup>³</sup> N⋅m/rad
		Maximum Rotating Speed	30,000min <sup>-1</sup>
		Working Temperature Range	-30 ~ +100 ⁰C
		Range of Bore Diameter	$\phi 2 \sim \phi 6$
	Fixing System	Set-Screw System	
Item	Type Unit/Symbol	U25F/	
Inertia (GD <sup>2/4</sup> )	kg ∙ m²	0.8 X 10*	
Max. Misalignment (Angular/Parallel)	%mm	1.5º/ 0.15	
Max. Axial Displacement	mm	0.5	
Weight	kg	0.010	
Outer Diameter	А	<i>ф</i> 18	
Bore Diameter	С	<i>φ</i> 2~ <i>φ</i> 6	
Space Between shaft	D	7	
Length of Hub	E	5.5	
Full Length	L	18	
Screw Position	1	3	
Screw Hole	Р	2-M3	
Tentative Hole Diameter	-	φ1.8	

\*Note 1 : Inner diameter in () is for a hub with greater boss diameter.

Note 2 : Maximum shaft diameter for that goes through inner diameter in flexible plates and spacers is  $\phi 5$ . Note 3 : Unit for figures without mention of unit is <mm>.

## **New Series**

Microfley

U25

M15

V15

Rated Torque 8N·m/12N·m 3.36X10<sup>3</sup>N·m/rad Torsional Rigidity ■Maximum Rotating Speed 20,000min<sup>-1</sup> Working Temperature Range -30 ~ +100 ⁰C Range of Bore Diameter *φ* 10 ~ *φ* 16

	Fixing System	Set-Screw System	Clamping System
Item	Type Unit/Symbol	M15FC-EBC/EBC	V15FC-EBC/EBC
Rated Torque	N · m	8	12
Inertia (GD <sup>2/4</sup> )	kg ∙ m²	32 X 10 <sup>-6</sup>	80 X 10-6
Max. Misalignment (Angular/Parallel)	%mm	1.5 <sup>°</sup> / 0.3	1.5 <sup>°</sup> / 0.3
Max. Axial Displacement	mm	1.2	1.3
Weight	kg	0.12	0.34
Outer Diameter	A	<i>φ</i> 48	φ 48
Bore Diameter	С	<i>φ</i> 10~ <i>φ</i> 16	<i>φ</i> 10~ <i>φ</i> 16
Space Between shaft	D	18	18
Length of Hub	E	18	18
Full Length	L	54	54
Screw Position	1	5.3	5.3
Screw Hole	Р	1-M5	1-M5
Tentative Hole Diameter	-	φ7.8	φ7.8
Body Material	-	Aluminum alloy	Carbon steel

Note 2 : Maximum shaft diameter for that goes through inner diameter in flexible plates and spacers is  $\phi 17$ .

Note 3 : Unit for figures without mention of unit is <mm>.

■Body Material:Aluminum alloy ■Flexible Plates:Stainless steel Bolt/Washer:Carbon steel





●U25F-3S/5S

9





#### Cautions for Handling

•A microcoupling develops high flexibility and greater torsional rigidity depending on elastic deformation. It must not, therefore, be dropped while handling it or causing it under excess load while mounting it. Failure in observing these cautions may cause unexpected failure or accident to take place.



#### **Business Lines**

#### **Compact and Thin Magnetic Brake**



#### Features

- •Torque:1kaf-cm and greater
- Outside Dimension:35mm and greater
- •Thickness:23.5mm and greater
- •Ease of mounting
- •Compact in size, smaller in thickness, but greater the maintained torque
- •Highly durable and heavily insulated against high temperature

#### Application

- •Best suitable to industrial robots, thin motors, special compact motors and the like.
- ODesigning and manufacture on optional specification are acceptable.

10

#### Cautions for Mounting

- •Microcoupling are, in general, delivered with finished bores, thus allowing mounting them as delivered.
- •Centering at mounting must be effected with maximum carefulness to 1/3 of tolerance so that mounted coupling may achieve their function to the full extent.
- •Check for burrs and/or flaws on shafts and/or bores in hubs. Also check to see if fitting between shafts is right.(Clearance fit is the most suitable, in general.)
- $\bullet Be$  sure not to cause excessive load placed on flexible plates for fitting hubs to shafts. Hold securely a hub in a hand to fit it over a shaft.
- •Check, on completion of fitting, to see if space between surfaces of flange on a coupling is right.(space must be within Å  $\{0.2 \text{ of }$ the space between shaftsÅkD DimensionÅl.)
- If the space between shafts is smaller than that between flange surfaces, move shafts so they will extruding inwardly to cause space between flange surfaces to be right. For doing so, be sure that shafts and inside diameter of spacers will not interfering each other.
- •After a test running for a short period of time, check for centering and rightness of such a test running.

#### Precision Belleville Spring



#### Features

- •Provides greater loading with a comparatively smaller space.
- •Arranging multiple number of one type of Belleville springs in parallel or serial positions allows for acquiring various spring properties.
- •Using various types of Belleville springs allows for acquiring nonlinear progressive loading properties.

#### Application

•Best suitable to machine tools, chucks in tools, pre-loading on bearings and the like.